
Math 215: Linear Algebra

PROBLEM SET 12 : DUE OCTOBER 2

(28 points) Make sure you are familiar with the Academic Honesty policies for this class, as detailed on the syllabus. All work is due on the given day by 3 PM Grinnell Time, or 7 PM if you LaTeX the assignment. **For this assignment, show all of your computational work.**

1. Suppose $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is the linear transformation with $[T] = \begin{pmatrix} 2 & -1 \\ 5 & 2 \end{pmatrix}$. Let $\vec{u}_1 = \begin{pmatrix} 1 \\ 3 \end{pmatrix}$ and $\vec{u}_2 = \begin{pmatrix} -2 \\ 0 \end{pmatrix}$ with $\alpha = (\vec{u}_1, \vec{u}_2)$.
 - (a) (2 points) Prove that $\text{Span}(\vec{u}_1, \vec{u}_2) = \mathbb{R}^2$.
 - (b) (2 points) Compute $[T(\vec{u}_1)]_\alpha$.
 - (c) (2 points) Compute $[T(\vec{u}_2)]_\alpha$.
 - (d) (1 point) Use (b) and (c) to compute $[T]_\alpha$.
2. (2 points) Repeat problem (1) but use Proposition 3.4.7 to determine $[T]_\alpha$ where $\alpha = (\vec{u}_1, \vec{u}_2)$.
3. (4 points) Let $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be the transformation defined by $T\left(\begin{pmatrix} x \\ y \end{pmatrix}\right) = \begin{pmatrix} rx \\ ry \end{pmatrix}$ where $r \in \mathbb{R}$ is arbitrary. Prove that for all bases $\alpha = (\vec{u}_1, \vec{u}_2)$ of \mathbb{R}^2 we have $[T] = [T]_\alpha$.
4. Suppose $[T] = \begin{pmatrix} 35 & 24 \\ -48 & -33 \end{pmatrix}$ and let $\alpha = \left(\begin{pmatrix} -2 \\ 3 \end{pmatrix}, \begin{pmatrix} -3 \\ 4 \end{pmatrix}\right)$ be a basis of \mathbb{R}^2 .
 - (a) (2 points) Compute $T(\vec{v})$ for **four** nonzero vectors $\vec{v} \in \text{Span}\left(\begin{pmatrix} -2 \\ 3 \end{pmatrix}\right)$.
 - (b) (2 points) Compute $T(\vec{v})$ for **four** nonzero vectors $\vec{v} \in \text{Span}\left(\begin{pmatrix} -3 \\ 4 \end{pmatrix}\right)$.
 - (c) (3 points) On one graph, carefully plot the eight vectors \vec{v} from (a) and (b) and the eight vectors $T(\vec{v})$ for those eight vectors. (It is ok to plot them as points in \mathbb{R}^2 instead of as vectors.) Geometrically describe what the transformation is doing to these vectors.
 - (d) (2 points) Use (c) to find values a and d so that $[T]_\alpha = \begin{pmatrix} a & 0 \\ 0 & d \end{pmatrix}$. Explain briefly your reasoning.
5.
 - (a) (3 points) Is the transformation $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ with $[T] = \begin{pmatrix} 3 & 1 \\ -1 & 1 \end{pmatrix}$ diagonalizable? If so, find some basis $\alpha = (\vec{u}_1, \vec{u}_2)$ so that $[T]_\alpha$ is a diagonal matrix.
 - (b) (3 points) Is the transformation $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ with $[T] = \begin{pmatrix} 1 & 2 \\ 3 & 2 \end{pmatrix}$ diagonalizable? If so, find some basis $\alpha = (\vec{u}_1, \vec{u}_2)$ so that $[T]_\alpha$ is a diagonal matrix.

6. (DO NOT TURN IN) Prove that for all 2×2 matrices A we have A is invertible if and only if 0 is not an eigenvalue of A . (Make sure you recall how to prove an *if and only if*.)